

Possibly Useful Information

Electric Force and Electric Fields:

$$\begin{aligned}\vec{F}_{12} &= \frac{kq_1q_2}{r^2} \hat{r} & q &= Ne & \vec{F} &= q\vec{E} & \vec{E} &= \frac{kq}{r^2} \hat{r} \\ \vec{E} &= \sum_i \vec{E}_i = \sum_i \frac{kq_i}{r_i^2} \hat{r}_i & \vec{E} &= \int d\vec{E} = \int \frac{k dq}{r^2} \hat{r} \\ \vec{p} &= q\vec{d} & \vec{\tau} &= \vec{p} \times \vec{E} & U &= -\vec{p} \cdot \vec{E} \\ \Phi &= \int \vec{E} \cdot d\vec{A} & \oint \vec{E} \cdot d\vec{A} &= \frac{q_{enc}}{\epsilon_0} \\ E &= \frac{q}{4\pi\epsilon_0 r^2} & E &= \frac{\lambda}{2\pi\epsilon_0 r} & E &= \frac{\sigma}{2\epsilon_0} & E_{cond} &= \frac{\sigma}{\epsilon_0} \\ \lambda &= \frac{Q}{L} = \frac{dq}{d\ell} & \sigma &= \frac{Q}{A} = \frac{dq}{dA} & \rho &= \frac{Q}{V} = \frac{dq}{dV}\end{aligned}$$

Electric Fields and Potentials:

$$\begin{aligned}\Delta U &= U_f - U_i = -W_{field} & U &= \frac{kq_1q_2}{r} & V &= \frac{kq}{r} \\ V &= \sum_i V_i = \sum_i \frac{kq_i}{r_i} & V &= \int dV = \int \frac{k dq}{r} \\ \Delta V &= V_f - V_i = -\frac{W_{field}}{q} = -\int_i^f \vec{E} \cdot d\vec{s} & \vec{E} &= -\nabla V = -\left(\frac{\partial V}{\partial x} \hat{i} + \frac{\partial V}{\partial y} \hat{j} + \frac{\partial V}{\partial z} \hat{k}\right)\end{aligned}$$

Capacitance:

$$\begin{aligned}q &= C\Delta V & C &= \frac{\epsilon_0 A}{d} & C &= 2\pi\epsilon_0 \frac{L}{\ln(b/a)} & C &= 4\pi\epsilon_0 \frac{ab}{b-a} \\ C &= 4\pi\epsilon_0 R & C_{eq} &= \sum_{j=1}^n C_j & \frac{1}{C_{eq}} &= \sum_{j=1}^n \frac{1}{C_j} \\ U &= \frac{q^2}{2C} = \frac{1}{2} C (\Delta V)^2 & u &= \frac{1}{2} \epsilon_0 E^2 & C &= \kappa C_0 & \epsilon_0 \oint \kappa \vec{E} \cdot d\vec{A} &= q\end{aligned}$$

Current, Resistance & Circuits:

$$\begin{aligned}I &= \frac{dq}{dt} & I &= \int \vec{J} \cdot d\vec{A} & I &= JA & \vec{J} &= ne\vec{v}_d & \vec{E} &= \rho\vec{J} \\ R &= \frac{V}{I} & \sigma &= \frac{1}{\rho} & R &= \frac{\rho L}{A} & \rho - \rho_0 &= \rho_0 \alpha (T - T_0) \\ P &= IV = I^2 R = \frac{V^2}{R} & P &= \frac{\Delta E}{\Delta t} & \mathcal{E} &= \frac{dW}{dq} & E &= q\Delta V \\ R_{eq} &= \sum_{j=1}^n R_j & \frac{1}{R_{eq}} &= \sum_{j=1}^n \frac{1}{R_j} & \Delta V_{loop} &= 0 & \sum I_{junc} &= 0 \\ I &= \left(\frac{\mathcal{E}}{R}\right) e^{-t/RC} & V_C &= \mathcal{E} (1 - e^{-t/RC}) & q &= q_0 e^{-t/RC} & I &= -\left(\frac{q_0}{RC}\right) e^{-t/RC} & \tau_C &= RC\end{aligned}$$

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Magnetic Fields:

$$\begin{aligned}
 \vec{F}_B &= q\vec{v} \times \vec{B} & F_B &= \frac{mv^2}{r} & \vec{F}_B &= I\vec{L} \times \vec{B} \\
 \mu &= NI\lambda & \vec{\tau} &= \vec{\mu} \times \vec{B} & U(\theta) &= -\vec{\mu} \cdot \vec{B} \\
 d\vec{B} &= \frac{\mu_0}{4\pi} \frac{Id\vec{s} \times \hat{r}}{r^2} & \oint \vec{B} \cdot d\vec{s} &= \mu_0 I_{enc} & \Phi_B &= \int \vec{B} \cdot d\vec{A} \\
 B &= \frac{\mu_0 I}{2\pi r} & B &= \frac{\mu_0 I \phi}{4\pi R} & B &= \mu_0 nI & B &= \frac{\mu_0 IN}{2\pi r} & B &= \frac{\mu_0 IR^2}{2(R^2 + x^2)^{3/2}}
 \end{aligned}$$

Magnetic Induction:

$$\begin{aligned}
 \mathcal{E} &= -\frac{d\Phi_B}{dt} & \oint \vec{E} \cdot d\vec{s} &= -\frac{d\Phi_B}{dt} & L &= \frac{N\Phi_B}{I} & \mathcal{E}_L &= -L \frac{dI}{dt} \\
 I &= \frac{\mathcal{E}}{R} (1 - e^{-t/\tau_L}) & I &= I_0 e^{-t/\tau_L} & \tau_L &= \frac{L}{R} \\
 U_B &= \frac{1}{2} LI^2 & u_B &= \frac{B^2}{2\mu_0} & \oint \vec{B} \cdot d\vec{A} &= 0
 \end{aligned}$$

LC Oscillations:

$$\begin{aligned}
 \omega^2 &= \frac{1}{LC} & q &= q_{\max} \cos(\omega t + \phi) \\
 q &= q_{\max} e^{-Rt/2L} \cos(\omega' t + \phi) & \omega' &= \sqrt{\omega^2 - (R/2L)^2} \\
 X_C &= \frac{1}{\omega_d C} & X_L &= \omega_d L & V_R &= I_R R & V_C &= I_C X_C & V_L &= I_L X_L \\
 Z &= \sqrt{R^2 + (X_L - X_C)^2} & \mathcal{E} &= \mathcal{E}_{\max} \sin \omega_d t & I &= I_{\max} \sin(\omega_d t - \phi) \\
 I_{\max} &= \frac{\mathcal{E}_{\max}}{Z} & \tan \phi &= \frac{X_L - X_C}{R} & I_{rms} &= \frac{I_{\max}}{\sqrt{2}} & \mathcal{E}_{rms} &= \frac{\mathcal{E}_{\max}}{\sqrt{2}} \\
 P_{ave} &= I_{rms}^2 R & P_{ave} &= I_{rms}^2 R = \mathcal{E}_{rms} I_{rms} \cos \phi \\
 \frac{V_{prim}}{N_{prim}} &= \frac{V_{sec}}{N_{sec}} & I_{prim} N_{prim} &= I_{sec} N_{sec} & R_{eq} &= \left(\frac{N_{prim}}{N_{sec}} \right)^2 R
 \end{aligned}$$

EM Waves:

$$\begin{aligned}
 \Phi_B &= \oint \vec{B} \cdot d\vec{A} = 0 & \oint \vec{B} \cdot d\vec{s} &= \mu_0 \epsilon_0 \frac{d\Phi_E}{dt} + \mu_0 I_{enc} & I_d &= \epsilon_0 \frac{d\Phi_E}{dt} \\
 E &= E_{\max} \sin(kx - \omega t) & \frac{E}{B} &= c & c &= \frac{1}{\sqrt{\mu_0 \epsilon_0}} & \vec{S} &= \frac{1}{\mu_0} \vec{E} \times \vec{B} \\
 B &= B_{\max} \sin(kx - \omega t) \\
 I_{point} &= \frac{P}{4\pi r^2} & F &= \frac{(2)IA}{c} & p &= \frac{F}{A} & I &= \frac{1}{2} I_0 & I &= I_0 \cos^2 \theta
 \end{aligned}$$

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Geometrical (Ray) Optics:

$$\theta_1 = \theta_2 \quad n_1 \sin \theta_1 = n_2 \sin \theta_2 \quad \theta_c = \sin^{-1} \frac{n_2}{n_1} \quad \theta_B = \tan^{-1} \frac{n_2}{n_1}$$

$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f} = \frac{2}{r} \quad \frac{1}{f} = \left(\frac{n_{lens}}{n_{med}} - 1 \right) \left(\frac{1}{r_1} - \frac{1}{r_2} \right) \quad m = -\frac{s_i}{s_o} \quad M = m_1 m_2 \dots$$

$$\frac{n_1}{p} + \frac{n_2}{i} = \frac{n_2 - n_1}{r} \quad m = -\frac{n_1 s_i}{n_2 s_o}$$

$s_o, s_i, f, r > 0$ in front of the mirror.

$s_o, s_i, f, r < 0$ behind the mirror.

$s_o > 0$ and $s_i, f, r < 0$ in front of the lens
or refracting surface.

$s_o < 0$ and $s_i, f, r > 0$ behind the lens
or refracting surface.

The radius of curvature of the lens surface first reached by the light rays is r_1 .

The curvature of the surface reached after the light passes through the lens is r_2 .

Interference and Diffraction:

$$m\lambda = d \sin \theta, m=0, 1, 2, \dots (\text{Bright}) \quad (m + \frac{1}{2})\lambda = d \sin \theta, m=0, 1, 2, \dots (\text{Dark})$$

$$2L = (m + \frac{1}{2})\frac{\lambda}{n}, m=0, 1, 2, \dots \quad 2L = m\frac{\lambda}{n}, m=0, 1, 2, \dots$$

$$\Delta\phi = \frac{2\pi}{\lambda} \Delta L \quad \text{Small } \theta: \sin \theta \approx \tan \theta \approx \theta$$

$$a \sin \theta = m\lambda, m=1,2,3,\dots (\text{Dark})$$

$$I(\theta) = I_m \left(\cos^2 \beta \right) \left(\frac{\sin \alpha}{\alpha} \right)^2 \quad \beta = \frac{\pi d}{\lambda} \sin \theta \quad \alpha = \frac{\pi a}{\lambda} \sin \theta$$

$$\sin \theta = 1.22 \frac{\lambda}{d} \quad \theta_R \approx 1.22 \frac{\lambda}{d} \quad D = \frac{\Delta\theta}{\Delta\lambda} = \frac{m}{d \cos \theta} \quad R = \frac{\lambda}{\Delta\lambda} = Nm$$

Constants & Conversions:

$$g = 9.81 \text{ m/s}^2 \quad e = 1.60 \times 10^{-19} \text{ C} \quad \epsilon_0 = 8.85 \times 10^{-12} \frac{\text{C}^2}{\text{Nm}^2}$$

$$m_p = 1.67 \times 10^{-27} \text{ kg} \quad m_e = 9.11 \times 10^{-31} \text{ kg}$$

$$k = \frac{1}{4\pi\epsilon_0} = 8.99 \times 10^9 \frac{\text{Nm}^2}{\text{C}^2} \quad \mu_0 = 4\pi \times 10^{-7} \frac{\text{T} \cdot \text{m}}{\text{A}} \quad c = 3.0 \times 10^8 \frac{\text{m}}{\text{s}}$$

$$1 \text{ eV} = 1.60 \times 10^{-19} \text{ J} \quad 1 \text{ V} = 1 \text{ J/C} \quad 1 \text{ W} = 1 \text{ J/s}$$

$$1 \text{ A} = 1 \frac{\text{C}}{\text{s}} \quad 1 \text{ T} = 1 \frac{\text{N}}{\text{A} \cdot \text{m}} \quad 1 \text{ H} = \frac{\text{T} \cdot \text{m}^2}{\text{A}} = 1 \Omega \cdot \text{s} \quad 1 \text{ F} = 1 \frac{\text{C}}{\text{V}} = 1 \frac{\text{s}}{\Omega}$$

$$C = 2\pi r \quad A_{cir} = \pi r^2 \quad A_{sph} = 4\pi r^2 \quad V_{sph} = (4/3)\pi r^3 \quad 180^\circ \text{ in } \Delta$$